

DE LA RECHERCHE À L'INDUSTRIE

Co-clustering de séries temporelles multivariées pour la validation du véhicule autonome

21 septembre 2021

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► 1. Industrial Context

▶ 2. Clustering of autonomous vehicle simulations

► 3. Co-clustering of autonomous vehicle simulations



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AD / ADAS: Huge increase of the number of systems



AD / ADAS: Huge increase of car complexity

ADAS ECU

Around view camera

Front camera

Radar

Lidar

Ultrasound barrier

Flight recorder

Redundant steering

Redundant braking

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AD / ADAS: Huge increase of car complexity

2015: <u>https://informationisbeautiful.net/visualizations/million-lines-of-code/</u>

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AD / ADAS: High reliability requirements

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Naive estimation of the required number of cars for validation

▶ For a reliability of 10⁻⁸ and a confidence of 95%, using a Poisson distribution we find

- Required driving time = 3 × 10⁸ hours
 Number of kilometers at 50kph = 1.5 × 10¹⁰ km

 $\approx 10^5$ cars should be dedicated to AD/ADAS validation

► A (partial) solution: numerical validation

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Typical design of experiment for AD/ADAS validation

Opportunities and challenges

Business opportunities from time series mining:

- Identify operating modes of the vehicle multivariate time series (co-)clustering problem
- Identify anomalies

Scientific challenges

- Many simulations (e.g. 10k)
- Many signals (e.g. 300)
- Many timesteps (signal sampling @ 20Hz)
- Dataset size up to 1Tb
- Different time series lengths per simulation

Clustering of AD / ADAS simulations

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Clustering of simulations via multivariate time series analysis

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From raw time series to simulation clustering

► Advanced Emergency Braking – Car to Car Rear Moving (AEB-CCRm)

- 20000 simulations
- Varying speeds
- Varying overlaps
- Analysis based on 30 signals

► Analysis performed with the reduced variant of the pipeline

Car speed w.r.t. time

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- ► Focus on multivariate time series: can we extract more informations?
- Yes: combine clustering with classification methods:
 - feature: design of experiment / input simulation parameters
 - label: assigned cluster

Car speed vs Overlap vs Cluster

Decision tree: DOE classification predicting cluster labels

Co-clustering of AD / ADAS simulations

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Model-based formulation

► Notations:

- $(x_{ijs})_{ijs}$, dataset with *n* observations of *p* features in *d* dimensions (ie. After FFT + PCA + PCA)
- Abuse of language and notations
 - the slice $(x_{ijs})_{is}$ is called a "**row**"
 - the slice $(x_{ijs})_{is}$ is called a "column"
 - the index *s* will be omitted
- $(z_{ik})_{ik}$ row cluster assignment variable
- $(w_{jl})_{il}$ column cluster assignment variable
- θ hyperparameters

Model based methods for clustering

- Partitions will be represented with a mixture model
- Cluster assignment uncertainty
- Probabilistic outlier detection

Model based formulation

Clustering with mixture models

$$p(x \mid \theta) = \sum_{z} p(x \mid z; \theta) p(z; \theta)$$

Co-clustering with latent block models

 $p(x \mid \theta) = \sum_{z,w} p(x \mid z, w; \theta) p(z; \theta) p(w; \theta)$

Multi-clustering with latent block models

$$p(x \mid \theta) = \sum_{z,w} p(x \mid z, w; \theta) p(z \mid w; \theta) p(w; \theta)$$

► Gaussian assumption à la GMM $p(x_{ij} | z_i = k, w_j = l; \theta) \sim N(\mu_{kl}, \Sigma_{kl})$

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Inference process & model selection

▶ Inference process for latent block models: Stochastic Gibbs EM

- SE step: sample $p(z, w | x, \theta)$ with a Gibbs sampler
 - Sample $p(z \mid w, x, \theta)$
 - Sample $p(w \mid z, x, \theta)$
- M step:
 - Update θ given (z, w)

► Model selection (MS) using the integrated classification likelihood

Issues

- Model selection is expensive
- Without MS, the user must input additional parameters

Possible solution: introduce non-parametric Dirichlet Process

► Useful formulation of the Dirichlet process $DP(\alpha, G_0)$ (Stick Breaking Process)

$$g_{k} \sim G_{0}, \qquad k = 1, \dots$$

$$\pi_{k}(\mathbf{r}) = r_{k} \prod_{\substack{h=1\\ \infty}}^{g_{k}} (1 - r_{h}), \qquad r_{h} \sim Beta(1, \alpha)$$

$$G = \sum_{\substack{k=1\\ k=1}}^{\infty} \pi_{k}(r)\delta_{g_{k}} \sim DP(\alpha, G_{0})$$

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Symmetric Dirichlet process for co-clustering

► Model formulation $x_{i,j} \mid \{z_i = k, w_j = l, \theta_{k,l}\} \sim F(\theta_{k,l}), \theta_{k,l} \sim G_0$ $z \sim Mult(\pi), w \sim Mult(\rho)$ $\pi_k(r) = r_k \prod_{h=1}^{k-1} (1 - r_h), r_h \sim Beta(1, \alpha)$ $\rho_l(s) = s_l \prod_{h=1}^{l-1} (1 - s_l), s_l \sim Beta(1, \beta)$

- **Bayesian Inference of** $p(z, w | x, \alpha, \beta, G_0)$ with a Gibbs sampler
 - Sample row assignments $p(z | x, w, \alpha, \beta, G_0)$ row by row with the CRP
 - Sample column assignments $p(w | x, z, \alpha, \beta, G_0)$ column by column with the CRP

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Complexity of the inference

$$O(npd^2 + (n+p)\overline{K}\overline{L}d^3)$$

Cereal Benchmark on a synthetic dataset

Synthetic dataset

- 5 row clusters with (20, 30, 40, 30, 20) observations
- 5 column clusters with (40, 20, 30, 20, 30) observations
- Each block has a Gaussian distribution
- 19600 time series

► Computer

- 12 processors Intel(R) Core(TM) i7-8850H CPU @ 2.60GHz
- 32 Gb RAM

Method	ARI	RI	NMI	Κ	runtime (s)
B-GMM	0.825	0.982	0.946	25	18.6
B - GMM_{MS}	0.942	0.994	0.9803	30	85.9
$B-GMM_{14}$	0.979	0.997	0.994	25	89.3
LBM	0.823	0.913	0.887	25	17.5
LBM_{MS}	0.940	0.994	0.979	25	494.4
LBM_{49}	1	1	1	25	603.2
B-DPMM	0.670	0.958	0.906	16	25.3
NPLBM	1	1	1	25	40

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Cea Use case: ELK

Emergency Lane Keeping (ELK)

- 400 simulations
- 22 variables
- Varying speeds
- Varying decentering
- Varying drifting angle
- ...

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Row clusters interpretations

Main row clusters:

- *Light Green:* drifting left and ELK fails
- Dark Green: drifting right and ELK fails
- Orange: ELK works

Lateral position in lane

Other row clusters are outliers:

• ELK system activates too late

Conclusions & perspectives

Summary Part I

- Industrial simulation clustering workflow from large time series database
- Main procedure in 4 steps
 - Vector representation of univariate time series
 - Dimension reduction of univariate vectors
 - Dimension reduction of multivariate components
 - Clustering in the reduced feature space
- Classification based methodology in order to interpret clusters

Summary Part II

- Use pre-processing pipelines for co-clustering
- Application of non-parametric co-clustering methodology for joined clustering of simulations and signals

Perspectives

- Better time series representation replace FFT with wavelets, polynomials, ...
- Scalability of the Dirichlet Process method
- Multi-clustering visualization

For more details:

- E. Goffinet, M. Lebbah, H. Azzag, L. Giraldi and A. Coutant. A New Multivariate Time Series Co-clustering Non-Parametric Model Applied to Driving-Assistance Systems Validation, AALTD 2021
- E. Goffinet, M. Lebbah, H. Azzag, L. Giraldi and A. Coutant. Multivariate Time Series Multi-Coclustering. Application to Advanced Driving Assistance System Validation. ESANN 2021

Merci de votre attention

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