

# Approche décentralisée d'insertion avec amélioration continue de la qualité de la solution pour un système TAD

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# On-Demand Transport

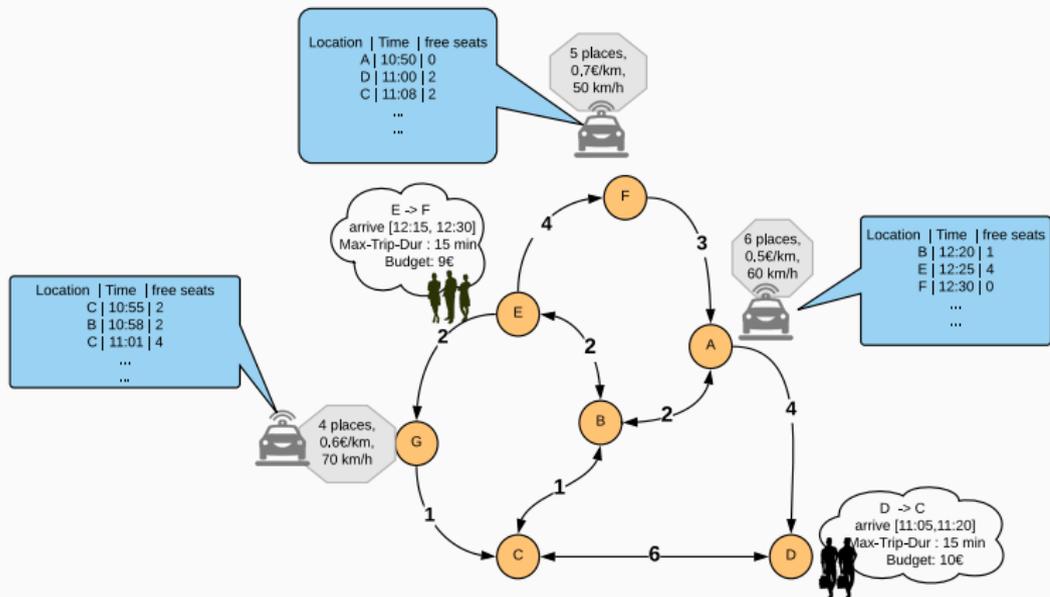
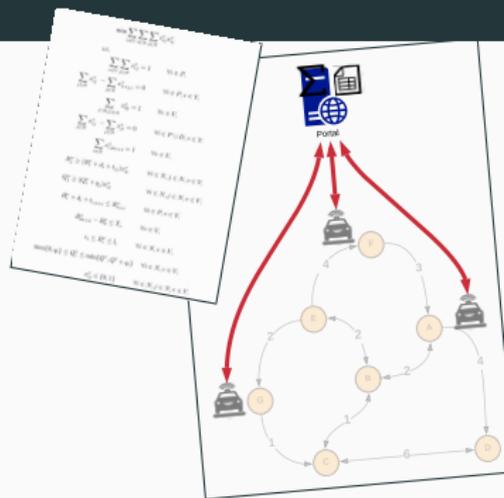


Figure 1: Dial A Ride Problem (DARP)

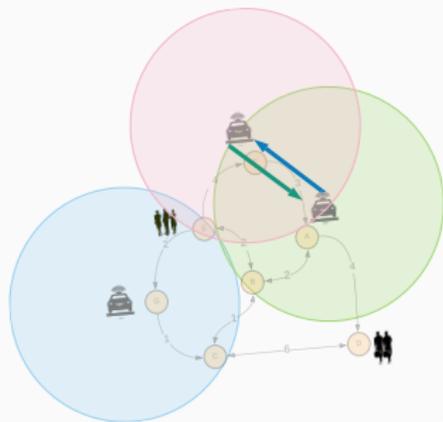
## "As is" model

- Requests are centralized in a portal
- Linear/ Mixed integer program models  
⇒ NP-Hard problem, lack of scalability for (environment, demand and supply) dynamics
- Continuous access to the portal  
⇒ expensive with a critical bottleneck



## "To be" model

- peer-to-peer (P2P) communication
- Decentralized decisions with coordination
- Equivalent performances with dynamic settings



## Objective: Decentralized solution $\Rightarrow$ Multi-agent

- Each vehicle is an autonomous agent: local goals (solve sub-problems)
- Global solution: aggregation of local solutions (never been calculated)
- Peer to Peer communication: scalable communication model is required

## Proposal: From individual decisions to global optimization

- Combinatorial auctions to allocate resources  $\Rightarrow$  feasible global solution
- Demand exchange strategies  $\Rightarrow$  optimize global solution
- Connection graph:
  - Global infrastructure:  $\Rightarrow$  complete graph
  - Scalable message passing management:  $\Rightarrow$  incomplete connected graph
  - Peer-to-Peer with connection range:  $\Rightarrow$  disconnected graph

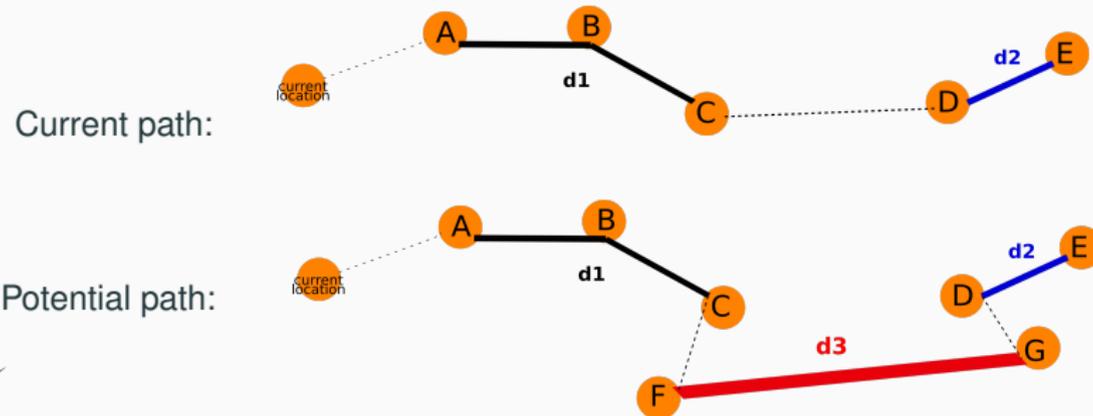
# Auction criteria

## Insertion-heuristic-based auctions

$$Bid_v^d(T_{start}, cost)$$

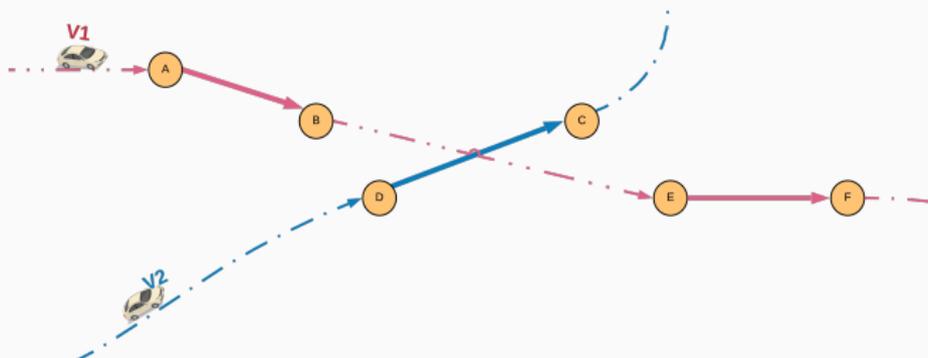
- $T_{start}$  : potential pick\_up time
- $cost$  : the marginal cost of inserting  $d$  in the schedule of  $v$

$$d3(F \rightarrow G)$$



## Improvement candidates

Each vehicle looks for requests that are scheduled by others and could be inserted in its schedule with lower cost.



**Figure 2:** V1 finds new candidate for improvement  $d(D \rightarrow C)$

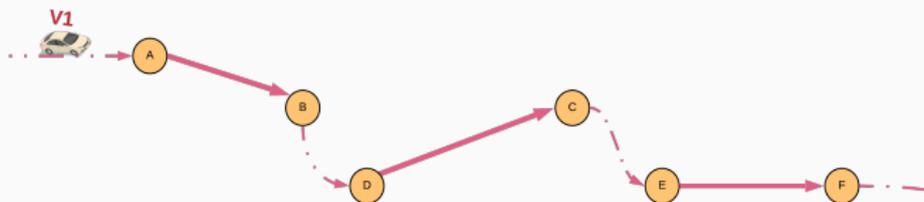
## Pull Auction

A vehicle  $V1$  may select one potential improvement candidate (request  $d$ ) a time (1-opt) and enter an auction with  $d$ 's serving vehicle  $V2$

$pull\_cost = V1$ 's marginal cost to insert  $d$

$pull\_gain = V2$ 's marginal cost to abandon  $d$

if ( $pull\_gain > pull\_cost$ ) :  $V1$  and  $V2$  update their schedules



**Figure 3:**  $V1$ 's potential improved schedule by inserting  $d(D \rightarrow C)$

- **Quality of service (QoS):** The number of satisfied requests
- **Quality of Business (QoB):** the simulated profit of the solution

$$profit = totalPriceIncome - totalMovingCost$$

where

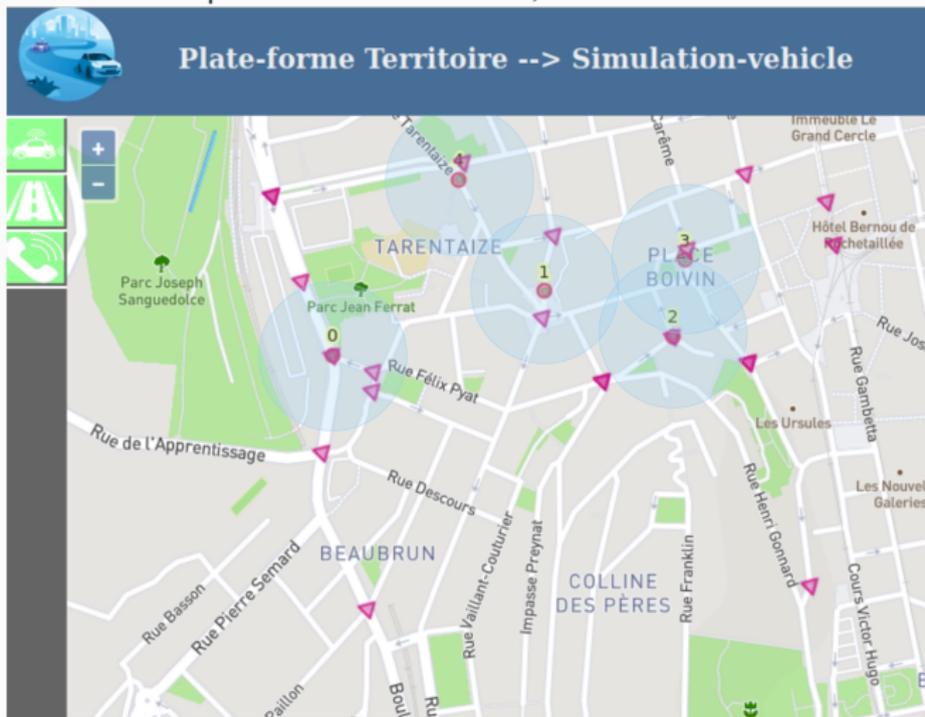
$$totalPriceIncome = \sum_{d \in D_s} T + p * distance_d$$

$$totalMovingCost = \sum_{v \in V} cpd_v * totalMovingDistance_v$$

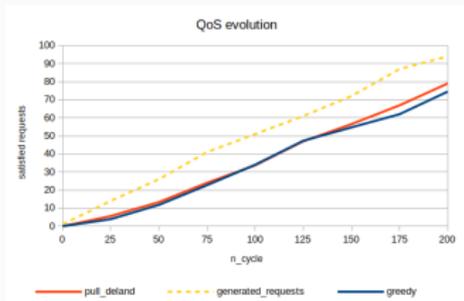
## Experimental settings

- **City map:** A graph structure  $G = \langle N, E \rangle$  of Saint Etienne extracted from OpenStreetMap (OSM). Distance between two consecutive points is 40 meters
- **Demand emission sources:** a set  $S \subset N : |S| = 20$ , having a set of edges  $E_S \subset E$ , such that  $|E_S| = 75$
- **Demand generation** At each simulation cycle, 0 or 1 request is generated randomly Each request has a source and a destination point generated randomly from the source set, and associated with a time window  $[tw_{min}, tw_{max}]$
- **Supply:** A fleet  $V$  of  $n$  vehicles is distributed randomly through  $S$  at the beginning of execution  
Each vehicle  $v \in V$  moves from one point to another on the same edge during each simulation cycle
- **Communication mean:** Dedicated Short Range Communication (DSRC) with a realistic communication range of 250m

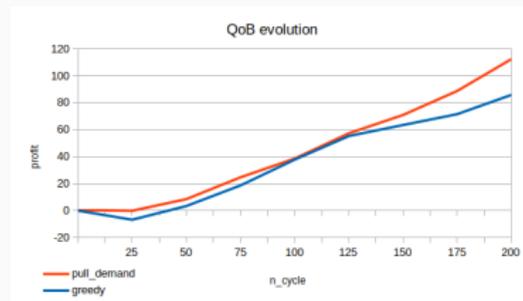
A discrete time transport simulator is used, included in *Plateforme Territoire*<sup>1</sup>



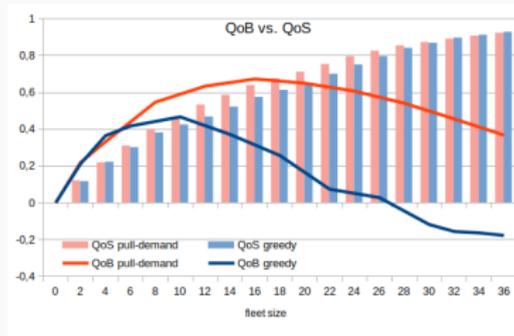
<sup>1</sup><https://territoire.emse.fr/>



**Figure 4:** Quality of service for a fleet of 16 vehicles



**Figure 5:** Quality of business for a fleet of 16 vehicles



**Figure 6:** Quality of business vs. quality of service evolution

## Our contribution

- A multi-agent model of ODT system
- Auction based coordination mechanism → fast feasible agreements
- Auction based rescheduling protocol → run-time optimization
- Comparison with greedy approach → preliminary feasibility evaluation

## On-going and future work

Implement a testbed for on-demand transport scheduling algorithms:

- Compare to centralized dispatching  
→ evaluate the solution optimality
- Compare with decentralized solutions (mainly DCOP)  
→ evaluate the communication behavior (message count and size)

Thank you!



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